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A Posteriori Error Estimators for Solutions to the Time Domain Maxwell Equations

M. L. Stowell, D. A. White

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A Posteriori Error Estimators for Solutions to the Time Domain Maxwell Equations

Mark L. Stowell, LLNL

Daniel A. White, LLNL

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Review of Maxwell's Equations

- Maxwell's Equations

$$\epsilon \frac{\partial \mathbf{E}}{\partial t} = \nabla \times \mathbf{H} - \mathbf{J}, \quad \nabla \cdot \mathbf{D} = 0, \quad \mathbf{D} = \epsilon \mathbf{E}$$

$$\mu \frac{\partial \mathbf{H}}{\partial t} = -\nabla \times \mathbf{E}, \quad \nabla \cdot \mathbf{B} = 0, \quad \mathbf{B} = \mu \mathbf{H}$$

- Wave Equation

$$\epsilon \frac{\partial^2 \mathbf{E}}{\partial t^2} = -\nabla \times \mu^{-1} \nabla \times \mathbf{E} - \frac{\partial \mathbf{J}}{\partial t}$$

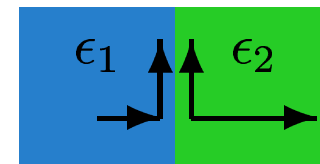
- Diffusion Equation

– assume $\sigma \mathbf{E} = \mathbf{J} + \epsilon \frac{\partial \mathbf{E}}{\partial t}$

$$\sigma \frac{\partial \mathbf{E}}{\partial t} = -\nabla \times \mu^{-1} \nabla \times \mathbf{E}$$

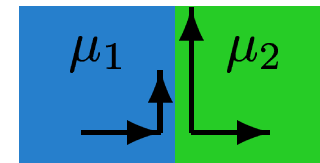
Continuity Considerations

Electric Field (\mathbf{E})



$$\hat{n} \times (\mathbf{E}_1 - \mathbf{E}_2) = 0, \quad \hat{n} \cdot (\mathbf{D}_1 - \mathbf{D}_2) = 0$$

Magnetic Flux (\mathbf{B})



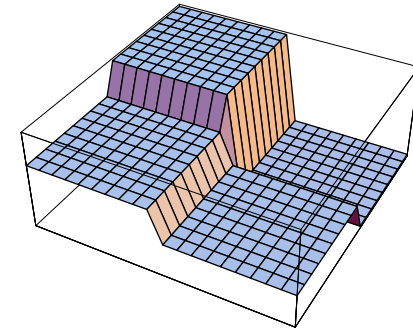
$$\hat{n} \times (\mathbf{H}_1 - \mathbf{H}_2) = 0, \quad \hat{n} \cdot (\mathbf{B}_1 - \mathbf{B}_2) = 0$$

Review of Patch Recovery Error Estimators

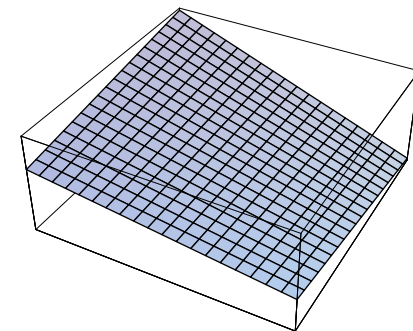


- In standard computational elasticity the primary variable is the displacement u . A linear u gives rise to a piecewise constant stress σ .
- Smoothing σ (computing nodal averages) gives a more palatable result to the user, and can be shown to be more accurate (Oden & Reddy, 1973.)
- The smooth (recovered) stress σ_r can be used to estimate the error in the computation (Zienkiewicz & Zhu, 1992,1993.)

Piecewise constant stress σ



Recovered stress σ_r

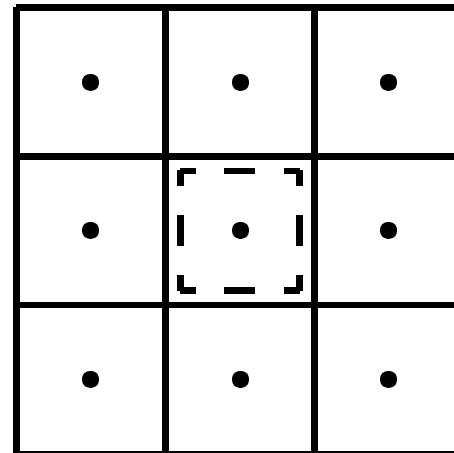
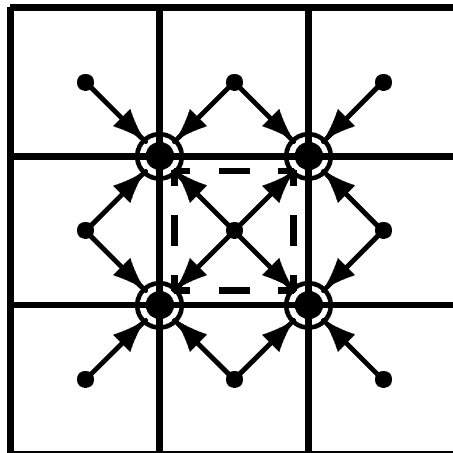


$$Error \approx |\sigma_r - \sigma|$$

Modified Patch Recovery for Maxwell's Equations



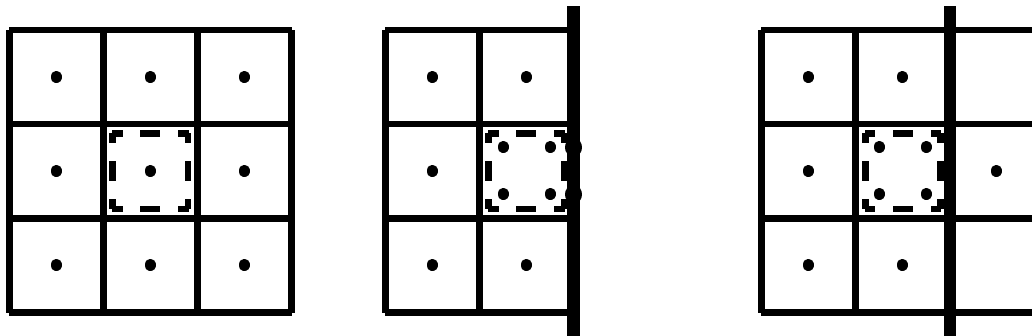
- Modification required
 - We want to process \mathbf{E} and \mathbf{B} directly, not the gradients
 - We need to deal with partial continuity of \mathbf{E} and \mathbf{B}
 - Cell-centered vs. node-centered



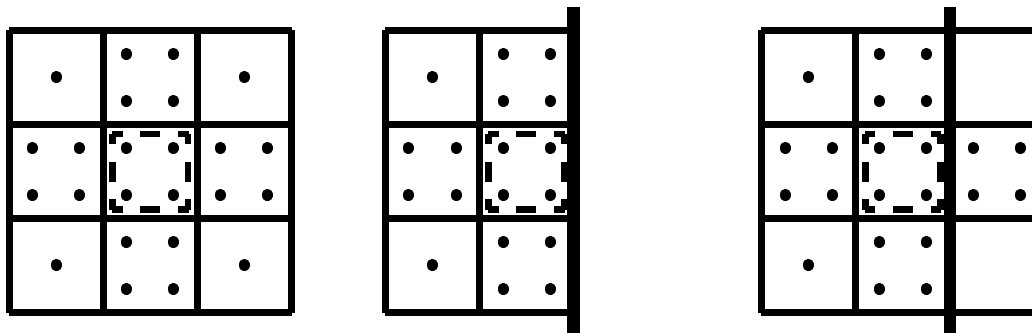
Sampling Points for Modified Patch Recovery



- $p = 1$ Biquadratic polynomial fit



- $p = 2$ Bicubic polynomial fit



Review of Explicit Residual Error Estimators



- For equations of the form:

$$\alpha \nabla \times \chi \nabla \times \mathbf{u}_n + \beta \mathbf{u}_n = \mathbf{f}(\mathbf{j}, \mathbf{u}_{n-1}, \dots)$$

- The error, $\mathbf{e} := \mathbf{u}(t_n) - \mathbf{u}_n$, satisfies the defect equation:

$$\alpha(\chi \nabla \times \mathbf{e}, \nabla \times \mathbf{q})_{L^2(\Omega)} + (\beta \mathbf{e}, \mathbf{q})_{L^2(\Omega)} = r(\mathbf{q}) \quad \forall \mathbf{q} \in H_0(\text{curl})$$

- Definition of the Residual:

$$r(\mathbf{q}) := (\mathbf{f}, \mathbf{q})_{L^2(\Omega)} - \alpha(\chi \nabla \times \mathbf{u}_n, \nabla \times \mathbf{q})_{L^2(\Omega)} - (\beta \mathbf{u}_n, \mathbf{q})_{L^2(\Omega)} \quad \forall \mathbf{q} \in H_0(\text{curl})$$

- Explicit Residual methods attempt to measure how closely a computed solution satisfies the differential equation.
- For an analysis of this method for Nédélec's edge elements see Beck, Hiptmair, Hoppe, and Wohlmuth, 2000

Explicit Residual Error Estimators for Maxwell's Equations



- Estimate consists of four separate terms

$$\nabla \cdot \mathbf{D} = 0 \quad \Rightarrow \quad \eta_0^T := h_T \left\| \frac{1}{\sqrt{\beta}} \nabla \cdot (\mathbf{f} - \beta \tilde{\mathbf{u}}) \right\|_{L^2(T)}, \quad T \in \mathcal{T}_h$$

$$\hat{\mathbf{n}} \cdot (\mathbf{D}_1 - \mathbf{D}_2) = 0 \quad \Rightarrow \quad \eta_0^F := h_F^{1/2} \left\| \frac{1}{\sqrt{\beta_A}} [\langle \mathbf{n}, \mathbf{f} - \beta \tilde{\mathbf{u}} \rangle]_J \right\|_{L^2(F)}, \quad F \in \mathcal{F}_h$$

$$\text{Diff. Eqn.} \quad \Rightarrow \quad \eta_1^T := h_T \left\| \frac{1}{\sqrt{\chi}} (\mathbf{f} - \alpha \nabla \times \chi \nabla \times \tilde{\mathbf{u}} - \beta \tilde{\mathbf{u}}) \right\|_{L^2(T)}, \quad T \in \mathcal{T}_h$$

$$\hat{\mathbf{n}} \times (\mathbf{H}_1 - \mathbf{H}_2) = 0 \quad \Rightarrow \quad \eta_1^F := h_F^{1/2} \left\| \frac{\alpha}{\sqrt{\chi_A}} [\mathbf{n} \times \chi \nabla \times \tilde{\mathbf{u}}]_J \right\|_{L^2(F)}, \quad F \in \mathcal{F}_h$$

Where

$$[\langle \mathbf{n}, \mathbf{q} \rangle]_J := \langle \mathbf{n}, \mathbf{q} \rangle|_{F \subset T_{out}} - \langle \mathbf{n}, \mathbf{q} \rangle|_{F \subset T_{in}} \quad \text{and} \quad [\mathbf{n} \times \mathbf{q}]_J := \mathbf{n} \times \mathbf{q}|_{F \subset T_{out}} - \mathbf{n} \times \mathbf{q}|_{F \subset T_{in}}$$

- The total error estimate is given by:

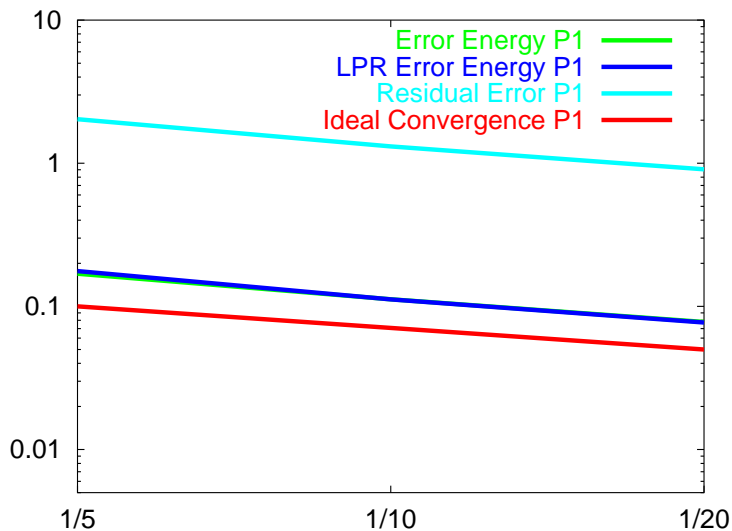
$$\eta_T^2 := (\eta_0^T)^2 + (\eta_1^T)^2 + \sum_{F \in \mathcal{F}(T) \cap \mathcal{F}^{int}} \frac{\beta|_T}{2\beta_A} (\eta_0^F)^2 + \frac{\chi|_T}{2\chi_A} (\eta_1^F)^2$$



Key Differences of the Two Methods

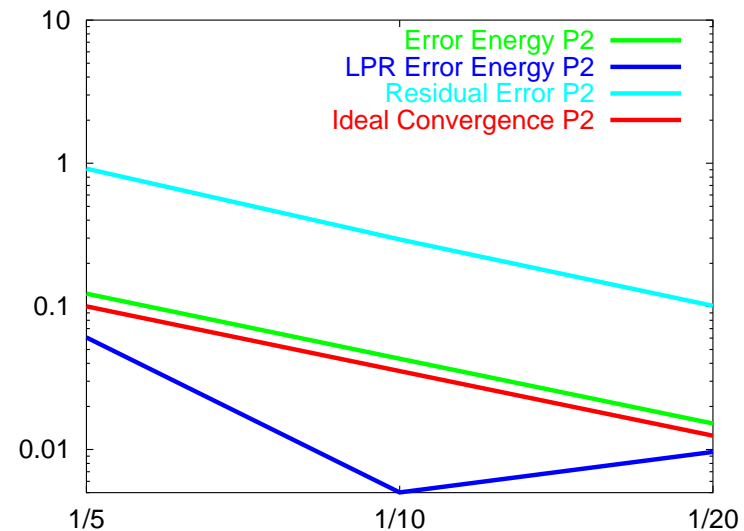
- Residual Methods
 - Not simply a measure of the curvature of the fields
 - Depends on both the field and its derivative
 - Takes into account the specific PDE being solved
 - Takes into account time integration
 - Can distinguish different types of errors
- Patch Recovery
 - Provides a smoother representation of the field
 - Computationally efficient

Convergence Results for the Diffusion Equation on a Distorted Mesh



$p = 1$

- True error and LPR overlap
- All measures converge at expected rate



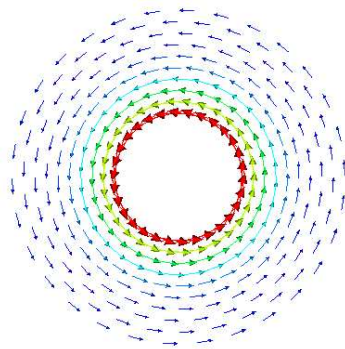
$p = 2$

- LPR is rather erratic
- Others converge at expected rate

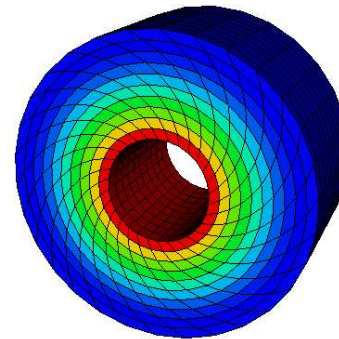
Error Distribution Results for the Diffusion Equation



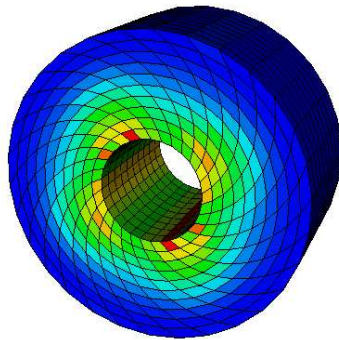
H
Field



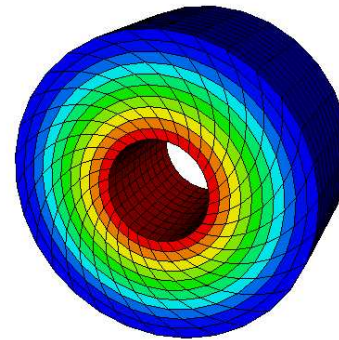
Error
Energy



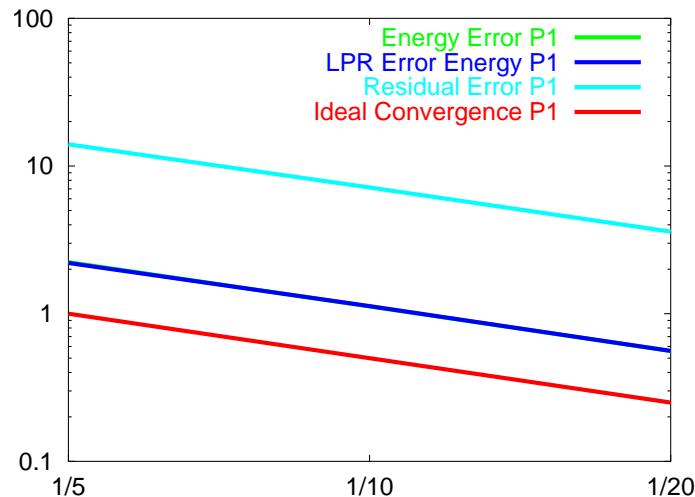
LPR
Error



Residual
Error

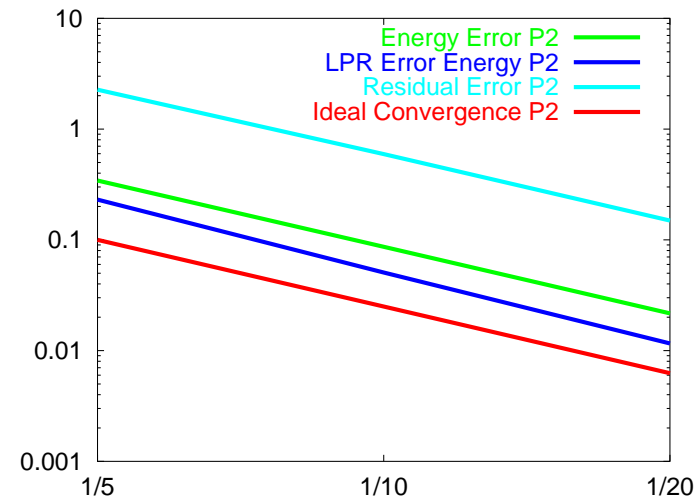


Convergence Results for the Wave Equation on a Cartesian Mesh



$p = 1$

- All errors show expected convergence rate (h^1)
- LPR matches global error but differs spacially



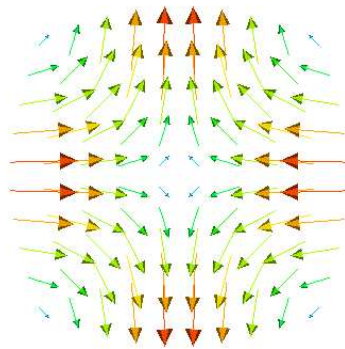
$p = 2$

- All errors show expected convergence rate (h^2)
- LPR under-estimates the error

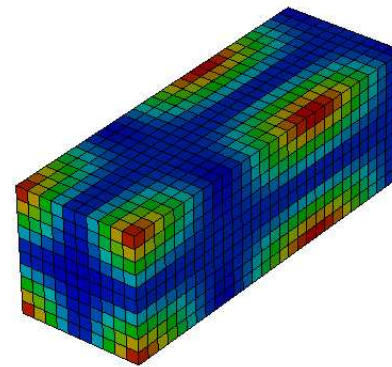
Error Distribution Results for the Wave Equation



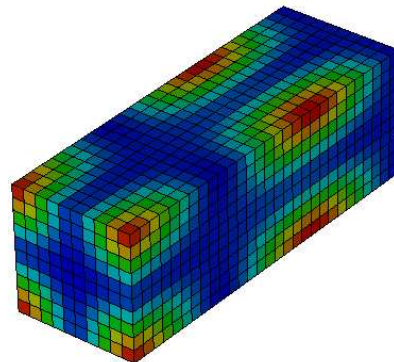
E
Field



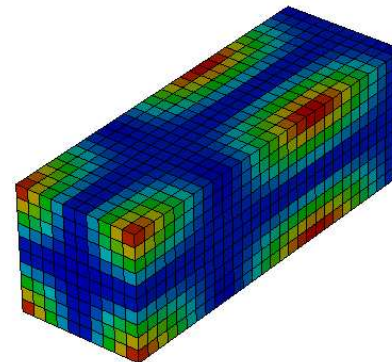
Error
Energy



LPR
Error



Residual
Error





Summary

- We developed and tested a modified patch recovery scheme for Maxwell's Equations
 - Computationally efficient
 - Provides a smoothed representation of the solution
- We implemented the Beck-Hiptmair-Hoppe-Wohlmuth explicit residual error estimator concept for both the wave equation and the diffusion equation
 - Works equally well throughout the mesh
 - Distinguishes errors arising from various characteristics of the solution
- Both methods...
 - account for jump discontinuity of fields across material interfaces
 - work for arbitrary order basis functions

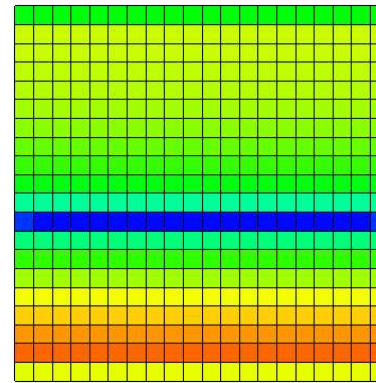
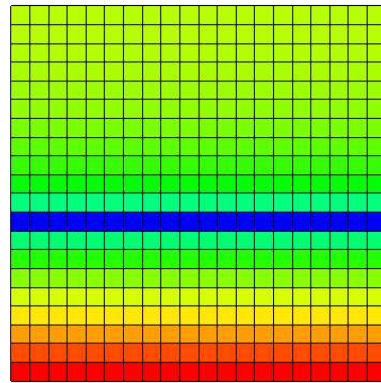
Questions...



Error Distribution Results for the Diffusion Equation on a Cartesian Mesh

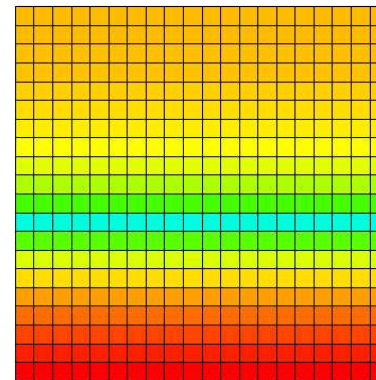
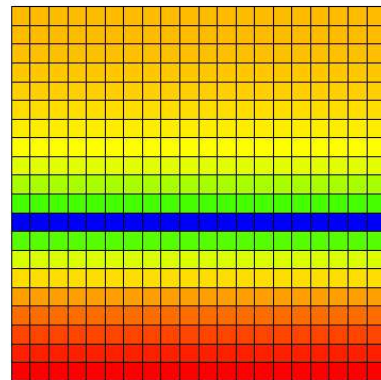


$$\|u - \tilde{u}\|_{L^2}^2$$



LPR
Error

$$\|\nabla \times (u - \tilde{u})\|_{L^2}^2$$



Residual
Error



Residual Based Error Estimation

$$\alpha \nabla \times \chi \nabla \times \mathbf{u}_n + \beta \mathbf{u}_n = \mathbf{f}$$

Where \mathbf{u} is the new iterative solution computed at a given time step and \mathbf{f} contains both the source term as well as the previous solutions.

- Vector Diffusion Equation for the Electric Field

$$\alpha = 1/2, \chi = \mu^{-1}, \beta = \sigma / dt$$

$$\mathbf{f} = -\partial_t \mathbf{J} - (1 - \alpha) \nabla \times \mu^{-1} \nabla \times \mathbf{u}_{n-1} + \frac{\sigma}{dt} \mathbf{u}_{n-1}$$

- Newmark Beta Scheme for the Second order Vector Wave Equation

$$\alpha = [0, 1], \chi = \mu^{-1}, \beta = \epsilon / dt^2$$

$$\mathbf{f} = -\partial_t \mathbf{J} - \nabla \times \mu^{-1} \nabla \times \{ (1 - 2\alpha) \mathbf{u}_{n-1} + \alpha \mathbf{u}_{n-2} \} + \frac{\epsilon}{dt^2} (2\mathbf{u}_{n-1} - \mathbf{u}_{n-2})$$



Definition of The Residual

$$r(\mathbf{q}) := (\mathbf{f}, \mathbf{q})_{L^2(\Omega)} - \alpha(\chi \nabla \times \tilde{\mathbf{u}}, \nabla \times \mathbf{q})_{L^2(\Omega)} - (\beta \tilde{\mathbf{u}}, \mathbf{q})_{L^2(\Omega)} \forall \mathbf{q} \in H_0(\text{curl})$$

Using $\mathbf{e} := \mathbf{u} - \tilde{\mathbf{u}}$ this definition becomes:

$$r(\mathbf{q}) = \alpha(\chi \nabla \times \mathbf{e}, \nabla \times \mathbf{q})_{L^2(\Omega)} + (\beta \mathbf{e}, \mathbf{q})_{L^2(\Omega)} \quad \forall \mathbf{q} \in H_0(\text{curl})$$

Which we then split in two pieces:

$$r(\mathbf{q}^0) = (\beta \mathbf{e}^0, \mathbf{q}^0)_{L^2(\Omega)} \quad \forall \mathbf{q}^0 \in H_0^0(\text{curl})$$

$$r(\mathbf{q}^\perp) = \alpha(\chi \nabla \times \mathbf{e}^\perp, \nabla \times \mathbf{q}^\perp)_{L^2(\Omega)} + (\beta \mathbf{e}^\perp, \mathbf{q}^\perp)_{L^2(\Omega)} \quad \forall \mathbf{q}^\perp \in H_0^\perp(\text{curl})$$

$$H_0^0(\text{curl}) := \{\mathbf{q} \in H_0(\text{curl}) \mid \nabla \times \mathbf{q} = 0\}$$

$$H_0^\perp(\text{curl}) := \{\mathbf{q} \in H_0(\text{curl}) \mid (\beta \mathbf{q}, \mathbf{q}^0)_{L^2(\Omega)} = 0 \quad \forall \mathbf{q}^0 \in H_0^0(\text{curl})\}$$



Resulting Error Terms

- Estimate consists of four separate terms

$$\nabla \cdot \mathbf{D} = 0 \quad \Rightarrow \quad \eta_0^T := h_T \left\| \frac{1}{\sqrt{\beta}} \nabla \cdot (\mathbf{f} - \beta \tilde{\mathbf{u}}) \right\|_{L^2(T)}, \quad T \in \mathcal{T}_h$$

$$\hat{\mathbf{n}} \cdot (\mathbf{D}_1 - \mathbf{D}_2) = 0 \quad \Rightarrow \quad \eta_0^F := h_F^{1/2} \left\| \frac{1}{\sqrt{\beta_A}} [\langle \mathbf{n}, \mathbf{f} - \beta \tilde{\mathbf{u}} \rangle]_J \right\|_{L^2(F)}, \quad F \in \mathcal{F}_h$$

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- The total error estimate is given by:

$$\eta_T^2 := (\eta_0^T)^2 + (\eta_1^T)^2 + \sum_{F \in \mathcal{F}(T) \cap \mathcal{F}^{int}} \frac{\beta|_T}{2\beta_A} (\eta_0^F)^2 + \frac{\chi|_T}{2\chi_A} (\eta_1^F)^2$$